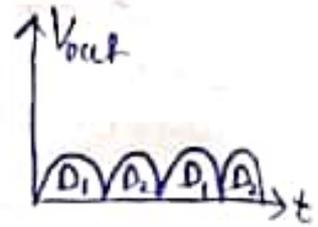
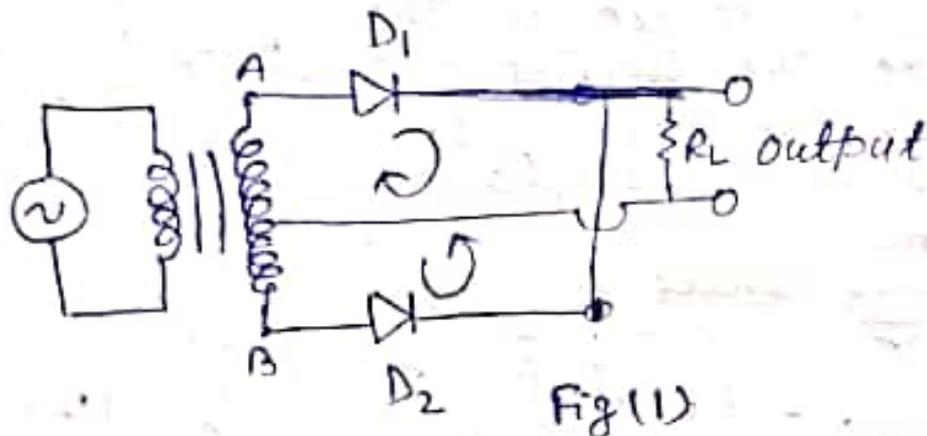


(1)

## Topic: - FULL WAVE RECTIFIER (UG-III)

A full wave rectifier circuit is shown in fig (1). It consists of two p-n junction diodes with a centre tapped transformer.



The output is obtained across load resistance  $R_L$  between terminals as shown. The input a.c. signal is supplied by the transformer on the secondary coil AB.

operation: - During the +ve half cycle of the input a.c., the end A of secondary winding is +ve and end B -ve, this makes  $D_1$  forward biased and  $D_2$  reverse biased. Thus,  $D_1$  conducts current and  $D_2$  does not conduct.

Similarly, during the -ve half cycle of input a.c., the end A and B of the secondary winding become -ve and +ve respectively. This makes  $D_1$  reverse biased and  $D_2$  forward biased, thus,  $D_2$  conducts and  $D_1$  is cut off.

(2)

Thus the current in the load  $R_L$  is in the same direction for both half cycle of input a.c. voltage. Thus, continuous output is obtained across  $R_L$  in the form of pulsating d.c.

## ANALYSIS OF FULL WAVE RECTIFIER

Let us consider an a.c. voltage  $V = V_0 \sin \omega t$  is to be rectified. If both the diodes  $D_1$  and  $D_2$  are supposed to be identical then the respective diode currents are given by

$$I_1 = \frac{V_0 \sin \omega t}{r + R_L} \quad \text{and} \quad I_2 = 0 \quad \text{for first half cycle} \\ \text{i.e. from } t = 0 \text{ to } t = \frac{T}{2}$$
$$= I_0 \sin \omega t \quad \text{--- (1a)}$$

$$\text{And } I_1 = 0; \quad I_2 = \frac{V_0 \sin(\omega t + \pi)}{r + R_L} \quad \text{--- (1b)}$$
$$= -\frac{V_0 \sin \omega t}{r + R_L} \quad \text{for next half cycle} \\ \text{i.e. from } t = \frac{T}{2} \text{ to } t = T$$
$$= -I_0 \sin \omega t$$

Here,  $I_1$  and  $I_2$  = current of two diodes  
 $r$  = a.c. resistance of each diode

$R_L$  = Load resistance

$\pi$  = phase difference between first and 2nd half cycle.



(3)

Now let us calculate the following things

(A) Output D.C. current and power. →  
 Since each diode conducts alternately for only half cycles of the input a.c. voltage, the d.c. current is given by

$$\begin{aligned}
 I_{dc} &= \frac{1}{T} \int_0^T I \, dt \\
 &= \frac{1}{T} \left[ \int_0^{T/2} I_1 \, dt + \int_{T/2}^T I_2 \, dt \right] \\
 &= \frac{1}{T} \left[ \int_0^{T/2} I_0 \sin \omega t \, dt + \int_{T/2}^T I_0 \sin \omega t \, dt \right] \\
 &= \frac{I_0}{T} \left[ \int_0^{T/2} (\sin \omega t) \, dt - \int_{T/2}^T (\sin \omega t) \, dt \right] \\
 &= \frac{I_0}{T} \left[ \left( -\frac{\cos \omega t}{\omega} \right) \Big|_0^{T/2} - \left( -\frac{\cos \omega t}{\omega} \right) \Big|_{T/2}^T \right] \\
 &= \frac{I_0}{T\omega} \left[ (\cos \omega t) \Big|_{T/2}^T - (\cos \omega t) \Big|_0^{T/2} \right] \\
 &= \frac{I_0}{T\omega} \left[ (\cos \frac{2\pi}{T} \cdot T - \cos \frac{2\pi}{T} \cdot \frac{T}{2} \right. \\
 &\quad \left. - (\cos \frac{2\pi}{T} \cdot \frac{T}{2} - \cos 0) \right] \\
 &= \frac{I_0}{T\omega} \left[ 1 - (-1) - (-1 - 1) \right] \\
 &= \frac{I_0}{T\omega} [2 + 2] = \frac{4 I_0}{T \cdot 2\pi} = \frac{2 I_0}{\pi}
 \end{aligned}$$

(4)

$$\therefore I_{dc} = \frac{2}{\pi} \cdot \frac{V_0}{r + R_L} \rightarrow (2) \quad (\because I_0 = \frac{V_0}{r + R_L})$$

The d.c. output voltage will be

$$V_{dc} = I_{dc} \times R_L = \frac{2 I_0 R_L}{\pi} = \frac{2}{\pi} \cdot \frac{V_0}{r + R_L} R_L \rightarrow (3)$$

The d.c. power output is given by

$$P_{dc} = I_{dc}^2 R_L = \frac{4 I_0^2}{\pi^2} R_L = \frac{4}{\pi^2} \cdot \frac{V_0^2}{(r + R_L)^2} R_L \rightarrow (4)$$

(B) A.C. input power:

If the total a.c. power input into the circuit is

$$P_{ac} = I_{rms}^2 (r + R_L) \rightarrow (5)$$

where,  $I_{rms} = \sqrt{\frac{1}{T} \left[ \int_0^{T/2} I_1^2 \, dt + \int_{T/2}^T I_2^2 \, dt \right]}$

$$= \sqrt{\frac{1}{T} \left\{ \int_0^{T/2} I_0^2 \sin^2 \omega t \, dt + \int_{T/2}^T I_0^2 \sin^2 \omega t \, dt \right\}}$$

$$= \left[ \frac{I_0^2}{T} \int_0^T \sin^2 \omega t \, dt \right]^{1/2} = \left[ \frac{I_0^2 \cdot T}{T} \right]^{1/2}$$

$$= \frac{I_0}{\sqrt{2}} \quad (\because \int_0^T \sin^2 \omega t \, dt = \frac{T}{2})$$

$$\therefore \text{from eqn (5)} \quad P_{ac} = \left( \frac{I_0}{\sqrt{2}} \right)^2 (r + R_L) = \frac{I_0^2}{2} (r + R_L) \rightarrow (6)$$

(C) Rectifier efficiency:

$$\eta_R = \left( \frac{P_{dc}}{P_{ac}} \times 100 \right) \% = \frac{8 R_L}{\pi^2 (r + R_L)} \times 100 \%$$

$$= \frac{81.2}{(1 + \frac{r}{R_L})} \%$$

Therefore, a full wave rectifier is twice as effective as half wave rectifier.

(D) Ripple Factor:  $r = \sqrt{\left( \frac{I_{rms}}{I_{dc}} \right)^2 - 1} = \sqrt{1.23 - 1} = 0.482$