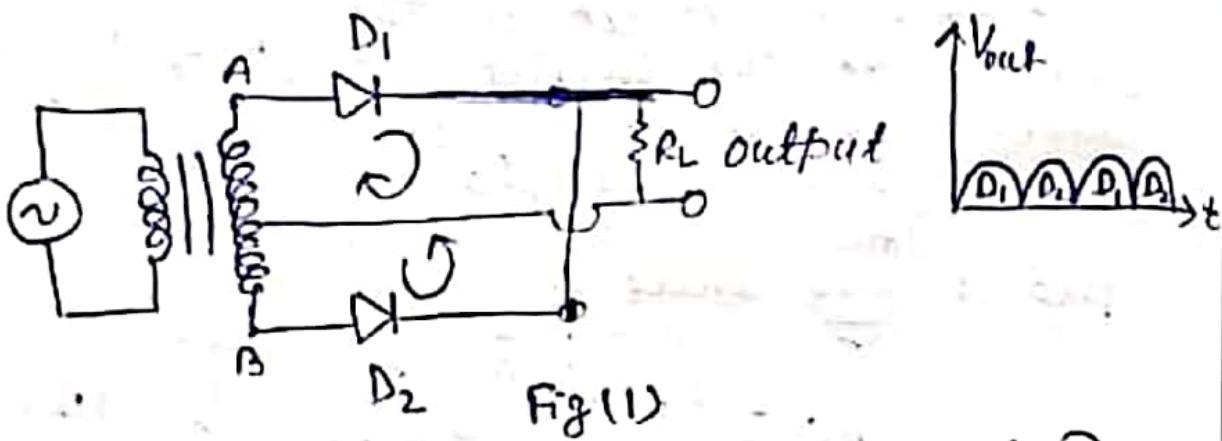


(1)

Topic:- FULL WAVE RECTIFIER (UG-III)

A full wave rectifier circuit is shown in fig(1). It consists of two p-n junction diodes with a centre tapped transformer.



- The output is obtained across load resistance R_L between terminals as shown.
- The input a.c. signal is supplied by the transformer on the secondary coil AB.

Operation:- During the +ve half cycle of the input a.c., the end A of secondary winding is +ve and end B -ve. This makes D_1 forward biased and D_2 reverse biased. Thus, D_1 conducts current and D_2 does not conduct.

Similarly, during the -ve half cycle of input a.c., the end A and B of the secondary winding become -ve and +ve respectively. This makes D_1 reverse biased and D_2 forward biased, thus, D_2 conducts and D_1 is cut off.

(2)

thus the current in the load R_L is in the same direction for both half cycle of input a.c. voltage. Thus, continuous output is obtained across R_L in the form of pulsating d.c.

ANALYSIS OF FULL WAVE RECTIFIER

Let us consider an a.c. voltage $E = E_0 \sin \omega t$ is to be rectified if both the diodes D_1 and D_2 are supposed to be identical then the respective diode currents are given by

$$I_1 = \frac{V_0 \sin \omega t}{\tau + R_L} \text{ and } I_2 = 0 \text{ for first half cycle}$$

i.e from $t = 0$ to $t = \frac{T}{2}$

$$= I_0 \sin \omega t \quad \rightarrow (1a)$$

$$\text{And } I_1 = 0; I_2 = \frac{V_0 \sin(\omega t + \pi)}{\tau + R_L}$$

$$= - \frac{V_0 \sin \omega t}{\tau + R_L} \text{ for next half cycle}$$

i.e from $t = \frac{T}{2}$ to $t = T$

$$= - I_0 \sin \omega t \quad \rightarrow (1b)$$

Here, I_1 and I_2 = Current of two diodes
 τ = a.c. resistance of each diode

R_L = Load resistance

π = phase difference between first and 2nd half cycle.



(3)

Now let us calculate the following things

(i) Output D.C. current and power. \rightarrow

Since each diode conducts alternately for only half cycles of the input A.C. voltage, the d.c. current is given by

$$I_{dc} = \frac{1}{T} \int_{T_0}^T I dt$$

$$= \frac{1}{T} \left[\int_{T_0}^{T_0} I_0 dt + \int_{T_0}^T I_0 dt \right]$$

$$= \frac{1}{T} \left[\int_{T_0}^{T_0} I_0 \sin \omega t dt + \int_{T_0}^T I_0 \sin \omega t dt \right]$$

$$= \frac{I_0}{T} \left[\int_{T_0}^{T_0} (\sin \omega t) dt - \int_{T_0}^T (\sin \omega t) dt \right]$$

$$= \frac{I_0}{T} \left[\left(-\frac{\cos \omega t}{\omega} \right) \Big|_{T_0}^{T_0} - \left(-\frac{\cos \omega t}{\omega} \right) \Big|_{T_0}^T \right]$$

$$= \frac{I_0}{T} \left[\left(\cos \omega t \right) \Big|_{T_0}^T - \left(\cos \omega t \right) \Big|_{T_0}^{T_0} \right]$$

$$= \frac{I_0}{T} \left[\left(\cos \frac{2\pi}{T} \cdot T - \cos \frac{2\pi}{T} \cdot T_0 \right) \right.$$

$$\left. - \left(\cos \frac{2\pi}{T} \cdot T_0 - \cos 0 \right) \right]$$

$$= \frac{I_0}{T} \left[1 - (-1) - (-1 - 1) \right]$$

$$= \frac{I_0}{T} \left[2 + 2 \right] = \frac{4I_0}{T} = \frac{2I_0}{\pi}$$

(4)

$$\therefore I_{dc} = \frac{2}{\pi} \cdot \frac{V_0}{r+R_L} \quad \rightarrow (2) \quad (r, I_0 = \frac{V_0}{r+R_L})$$

The d.c. output voltage will be

$$V_{dc} = I_{dc} \times R_L = \frac{2I_0}{\pi} R_L = \frac{2}{\pi} \cdot \frac{V_0}{(r+R_L)} R_L \quad \rightarrow (3)$$

The d.c. power output is given by

$$P_{dc} = I_{dc}^2 R_L = \frac{4I_0^2}{\pi^2} R_L = \frac{4}{\pi^2} \frac{V_0^2}{(r+R_L)^2} R_L \quad \rightarrow (4)$$

(5) A.C. Input power:

$$\text{Imp. into the circuit} \quad \rightarrow (5)$$

$$P_{ac} = I_{ac}^2 (r+R_L) \quad \rightarrow (5)$$

$$\text{where, } I_{ac} = \frac{1}{T} \int_{T_0}^T I dt = \left[\frac{1}{T} \left\{ \int_{T_0}^{T_0} I dt + \int_{T_0}^T I dt \right\} \right]^{T_0}_T$$

$$= \left[\frac{1}{T} \left\{ \int_{T_0}^{T_0} \sin^2 \omega t dt + \int_{T_0}^T \sin^2 \omega t dt \right\} \right]^{T_0}_T$$

$$= \left[\frac{1}{T} \int_{T_0}^T \sin^2 \omega t dt \right]^{T_0}_T = \left[\frac{T_0}{2}, \frac{T}{2} \right]^{T_0}_T$$

$$= \frac{I_0}{\sqrt{2}} \quad \left(\because \int_{T_0}^T \sin^2 \omega t dt = \frac{T}{2} \right)$$

$$= \frac{I_0}{\sqrt{2}} \quad \left(\because \int_{T_0}^T \sin^2 \omega t dt = \frac{T}{2} \right) \quad \rightarrow (6)$$

$$\therefore \text{From eqn (5)} \quad P_{ac} = \left(\frac{I_0}{\sqrt{2}} \right)^2 (r+R_L) = \frac{I_0^2}{2} (r+R_L)$$

$$= \frac{I_0^2}{2\pi} \quad \rightarrow (6)$$

(6) Rectification efficiency:

$$\eta_R = \left(\frac{P_{dc}}{P_{ac}} \times 100 \right) \% = \frac{8R_L}{\pi(r+R_L)} \times 100\%$$

$$= \frac{8I_0^2}{(\pi + \frac{r}{R_L})} \eta$$

Therefore, a full wave rectifier is twice as effective as half wave rectifier. $\eta = \sqrt{2.5 - 1} = 0.482$

(D) Ripple Factor: $F = \sqrt{\left(\frac{I_{acm}}{I_{ac}} \right)^2 - 1} = \sqrt{1.25 - 1} = 0.482$

THE END