

Basis of a Vector Space:

DP

A subset S of a vector space V over a field F i.e. $V(F)$ is said to be a basis of $V(F)$, if follows these properties.

- (i) S consists of linear independent vectors.
- (ii) S generates $V(F)$ i.e. $L(S) = V$ i.e. each vector in V is a linear combination of a finite number of elements of S .

$$V = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_k v_k$$

where $v_1, v_2, v_3, \dots, v_k$ are distinct vectors from S and $\alpha_1, \alpha_2, \dots, \alpha_k \in F$ (real numbers)

Example (i) Standard basis for $V(\mathbb{R}^n)$ or $V_n(\mathbb{R})$
 $e_1 = (1, 0, 0, \dots, 0, 0)$, $e_2 = (0, 1, 0, 0, \dots, 0, 0)$
 $e_3 = (0, 0, 1, 0, 0, \dots, 0, 0)$... $e_n = (0, 0, 0, \dots, 0, 0, 1)$

(ii) Matrices $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$
form a basis for $M_{2 \times 2}(\mathbb{R})$

(iii) Polynomials $1, x, x^2, \dots, x^{n-1}$ form a basis for
 $P_n = \{a_0 + a_1 x + a_2 x^2 + \dots + a_{n-1} x^{n-1}; a_i \in \mathbb{R}\}$

(iv) The infinite set $\{1, x, x^2, \dots, x^n, \dots\}$ is a basis for P , the space of all polynomials.

(v) The zero space $\{0\}$ has no basis

(vi) Every non-zero vector space has a basis

(vii) Every finite generated vector space has basis.

(viii) A vector space may have more than one basis.

Exp Let $S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ forms a basis of $V(\mathbb{R}^3)$ and is called usual basis $V(\mathbb{R}^3)$ read as Vector space V over \mathbb{R} (real numbers) in 3-dimensions.

Exp Determine whether or not the vectors $(1, -3, 2)$, $(2, 4, 1)$ and $(1, 1, 1)$ form a basis of \mathbb{R}^3 .

Sol. We know dimension of $\mathbb{R}^3 = 3$.

If we show that the given vectors are linearly independent, then they form a basis of \mathbb{R}^3 .

Let $\alpha, \beta, \gamma \in \mathbb{R}$ i.e. 3 scalars.

then $\alpha(1, -3, 2) + \beta(2, 4, 1) + \gamma(1, 1, 1) = 0$

$$\begin{aligned} \alpha + 2\beta + \gamma &= 0 \text{ --- (i)} \\ -3\alpha + 4\beta + \gamma &= 0 \text{ --- (ii)} \\ 2\alpha + \beta + \gamma &= 0 \text{ --- (iii)} \end{aligned} \Rightarrow \begin{vmatrix} 1 & 2 & 1 \\ -3 & 4 & 1 \\ 2 & 1 & 1 \end{vmatrix} = A$$

$$|A| = 1(4-1) - 2(-3-2) + 1(-3-8)$$

$$= 3 + 12 - 11 = 4 \neq 0 \text{ So, the above Eqn possesses only trivial solution } \alpha = \beta = \gamma = 0$$

Since the determinant of vectors (matrix A) is not equal to zero i.e. $|A| \neq 0$, so the given vectors are ~~not~~ linearly independent and so so form of basis of \mathbb{R}^3 is set of vectors.

$S = \{(1, -3, 2), (2, 4, 1), (1, 1, 1)\}$ forms a basis of \mathbb{R}^3 .

Exp. Show that the set $S = \{(1, 0, 0), (0, 1, 0), (4, 5, 0)\}$ is not a basis of \mathbb{R}^3

Sol. The set S of vectors written in matrix and find determinant. $A = \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow |A| = 1(0) - 0(0) + 4(0) = 0$

Thus S is linear dependent and so S cannot be a basis of \mathbb{R}^3

* Dimension of a Vector Space - If a vector space V over F has a finite basis having n vectors, then n is called the dimension of V over F and is written as $\dim_F(V) = n$ or $\dim V(F) = n$

→ If V does not have a finite basis, then V is called an infinite dimensional vector space.

Remark - (i) The dimension of null space $\{0\}$ is defined as

zero

(ii) If $\dim V(F) = n$, then V has a basis containing n vectors, say $S = \{v_1, v_2, \dots, v_n\}$

The vectors $v_1, v_2, v_3, \dots, v_n$ are linearly independent over F and each $v \in V$ is expressible as $v = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n$, $\alpha_i \in F$

(iii) If V is a finite dimension vector space (F -DVS) then any two basis of V have the same number of elements. Hence the dimension of V is uniquely defined.

Exps. (i) $\dim \mathbb{R}^2 = 2$, since $\{(1,0), (0,1)\}$ is a basis of \mathbb{R}^2
 (ii) $\dim \mathbb{R}^3 = 3$, since $\{(1,0,0), (0,1,0), (0,0,1)\}$ is a basis of \mathbb{R}^3
 (iii) $\dim \mathbb{R}^n = n$, since $\{e_1 = (1,0,0, \dots, 0), e_2 = (0,1,0, \dots, 0), \dots, e_n = (0,0,0, \dots, 1)\}$ is a basis of \mathbb{R}^n .

(iv) $\dim_{\mathbb{R}} \mathbb{C}$ or $\dim \mathbb{C}(\mathbb{R}) = 2$, since $\{1, i\}$ is a basis of \mathbb{C} over \mathbb{R}

(v) If F is any field, then $\dim_{\mathbb{Z}} F = 1$; since $\{1\}$, consisting of the unity of F , is a basis of F over \mathbb{Z} .

In particular, $\dim_{\mathbb{R}} \mathbb{R} = 1$, $\dim_{\mathbb{C}} \mathbb{C} = 1$

(vi) Let $F_n[x]$ be the vector space of all polynomials (over a field F) with degree less than n . Then $\dim F_n[x] = n$, since $\{1, x, x^2, \dots, x^{n-1}\}$ is a basis of $F_n[x]$ over F .