

## Differential Calculus :-

In this, study of fundamental ideas of the Integration & Differential Calculus.

→ The fundamental limiting processes of calculus are integration and differentiation.  $t = \int_a^b f(x) dx$   
i.e.  $\frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$

## Differentiation (the concept of rate of change)

It is the concept needed for describing the notions of tangents to curves - and of velocity of moving particles, or more generally, the concept of rate of change. Thus, differentiation is the derivative of the function  $y = f(x)$  with respect to  $x$ , denoted as  $f'(x)$  or  $\frac{dy}{dx}$ .

It is define as the slope of the tangent line to the curve  $y = f(x)$  at the point  $P(x, y)$

This slope is obtained by a limit as:  $(\lim_{\Delta x \rightarrow 0} \frac{\Delta y}{\Delta x})$

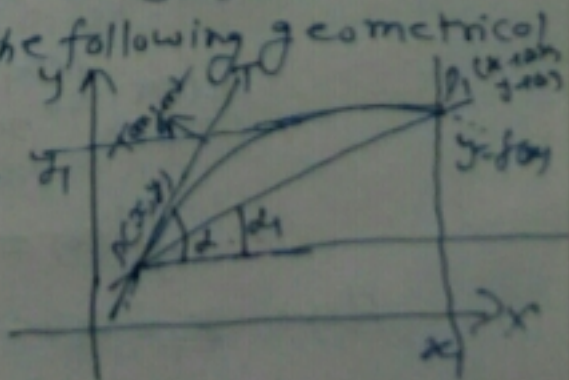
$$\frac{dy}{dx} = f'(x) = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$$

## Geometrical Definition :- We define the

tangent to the given curve  $y = f(x)$  at one of its points by means of the following geometrical limiting process.

Let  $P_1(x+\Delta x, y+\Delta y)$  near  $P(x, y)$  on the curve.

$PP_1$  is the secant of the curve.



→ If now the point  $P_1$  moves along the curve towards the point  $P$ , then the secant is expected to approach a limiting position which is independent of the side from which  $P_1$  tends to  $P$ .

Hence, this limiting position of the secant is the tangent; the statement such that a limiting position of the secant exists is equivalent to the assumption that curve has a definite tangent or a definite direction at the point  $P$ .

Since our curve is represented by means of a function  $y=f(x)$ , we must formulate the geometric limiting process analytically, with reference to  $f(x)$ . This analytical limit process is called differentiation of  $f(x)$ .

Let  $\alpha_1$  be the angle which the secant ( $PP_1$ ) with  $x$ -axis and  $\alpha$  angle which the tangent ( $T$ ) forms with  $px$  axis.

Then  $\lim_{P_1 \rightarrow P} \alpha_1 = \alpha$

$$\tan \alpha_1 = \frac{y_1 - y}{x_1 - x} = \frac{f(x_1) - f(x)}{x_1 - x} = \frac{\Delta y}{\Delta x}$$

$$\lim_{x_1 \rightarrow x} \frac{f(x_1) - f(x)}{x_1 - x} = \lim_{x_1 \rightarrow x} \tan \alpha_1 = \tan \alpha$$

$$f'(x) = \frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\Delta y}{\Delta x}$$

Here  $x_1 = x + \Delta x$  &  $y_1 = y + \Delta y$



## Successive Differentiation

The process of differentiating a function again and again is called successive differentiation.

or. A function is differentiating  $n$  times called successive differentiation of  $n$ th derivatives.

If  $y = f(x)$ , then its successive derivatives are denoted by -  $\frac{dy}{dx}$ ,  $\frac{d^2y}{dx^2}$ ,  $\dots$ ,  $\frac{d^ny}{dx^n}$ .

$\left[ \therefore \frac{dy}{dx} \rightarrow \text{steepness of a curve at point } (x, y) \right]$   
= slope of a tangent to the curve at the point  $(x, y)$ , where  $y$  is a function of  $x$  i.e.  $y = f(x)$ .  
 $\frac{dy}{dx}$  or  $f'(x)$  or  $y_1$  is called the first derivative of  $y$  w.r.t.  $x$ .

Exp. To find the  $n$ th derivatives of  $x^m$ .

Sol. Given that  $y = x^m$  — (1)

Differentiating Eqn (1) both sides w.r.t.  $x$  again and again, we get

$$\frac{dy}{dx} = y_1 = mx^{m-1}$$

$$\frac{d^2y}{dx^2} = y_2 = m(m-1)x^{m-2}$$

$$\frac{d^3y}{dx^3} = y_3 = m(m-1)(m-2)x^{m-3}$$

$$\frac{d^ny}{dx^n} = y_n = m(m-1)(m-2)\dots(m-(n-1))x^{m-n} \quad \text{--- (2)}$$

Again, differentiating Eq (2), we get

$$\frac{d^{n+1}y}{dx^{n+1}} = J_{n+1} = m(m-1)(m-2)\dots(m-n+1)(m-n)x^{m-(n+1)}$$

Hence,  $y_{n+1}$  is of the same form  $y_n$ , given by equation (2). This  $\Rightarrow$  If Eq (2) is true for  $n$  value then Eq (2) is true for next higher value of  $n$  also. It is true for  $n=1, 2, 3, \dots$  and so on.  
From Eq (2) we can write  $y_n$  as follows:-

$$y_n = \frac{m(m-1)(m-2)\dots(m-n+1)(m-n)(m-n+1)\dots 3 \cdot 2 \cdot 1}{(m-n)(m-n+1)\dots 3 \cdot 2 \cdot 1} x^{m-n}$$

$$y_n = \frac{m!}{(m-n)!} x^{m-n} \quad \text{--- (3)}$$

Corollary if  $y = x^n$ , then  $y_n = n!$

$$\therefore y = x^m \Rightarrow y_n = \frac{m!}{(m-n)!} x^{m-n}$$

but  $m=n$  then

$$y = x^n \Rightarrow y_n = \frac{n!}{(n-n)!} x^{n-n} = \frac{n!}{1} \cdot 1 = \underline{\underline{n!}}$$

From (3) for  $n=1$

$$y_1 = \frac{m!}{(m-1)!} x^{m-1} = \frac{m \cdot \cancel{(m-1)!}}{\cancel{(m-1)!}} x^{m-1} = m x^{m-1}$$

for  $n=2$

$$y_2 = \frac{Lm}{Lm-2} x^{m-2} = \frac{m(m-1) \cancel{Lm-2}}{\cancel{Lm-2}} x^{m-2}$$

$$= m(m-1) x^{m-2}$$

for  $n=3$

$$y_3 = \frac{Lm}{Lm-3} x^{m-3} = \frac{m(m-1)(m-2) \cancel{Lm-3}}{\cancel{Lm-3}} x^{m-3}$$

$$y_3 = m(m-1)(m-2) x^{m-3}$$

and so on.  $\dots =$