

## \* Muller's Method :-

In this method, the given function  $f(x)$  is approximated by a second degree curve in the vicinity of a root. The roots of the quadratic are then assumed to be the approximations to the roots of the equations  $f(x)=0$ . The method is iterative and can be used to compute complex roots. It has quadratic convergence.

Let  $(x_{i-2}, y_{i-2})$ ,  $(x_{i-1}, y_{i-1})$  and  $(x_i, y_i)$  be three distinct points on the curve  $y=f(x)$  where  $x_{i-2}$ ,  $x_{i-1}$  and  $x_i$  are approximations to a root of  $f(x)=0$ . Now, a second degree curve passing through the three points is given Lagrange's formula -

$$L(x) = \frac{(x-x_{i-1})(x-x_i)}{(x_{i-2}-x_{i-1})(x_{i-2}-x_i)} y_{i-2} + \frac{(x-x_{i-2})(x-x_i)}{(x_{i-1}-x_{i-2})(x_{i-1}-x_i)} y_{i-1} + \frac{(x-x_{i-2})(x-x_{i-1})}{(x_i-x_{i-2})(x_i-x_{i-1})} y_i \quad \text{--- (1)}$$

$$\text{Let } h_i = x_i - x_{i-1}, \quad h_{i-1} = x_{i-1} - x_{i-2} \quad \text{--- (2)}$$

$$\text{Then } \left. \begin{aligned} x - x_{i-1} &= x - x_i + x_i - x_{i-1} = (x - x_i) + h_i \\ x - x_{i-2} &= x - x_i + x_i - x_{i-2} = (x - x_i) + (h_{i-1} + h_i) \\ x_{i-2} - x_{i-1} &= -h_{i-1} \\ x_{i-2} - x_i &= -(h_{i-1} + h_i) \text{ and } \Delta_i = y_i - y_{i-1} \end{aligned} \right\} \text{--- (3)}$$

Hence

$$L(x) = \frac{(x-x_{i+1}+h_i)(x-x_i)}{h_{i-1}(h_{i-1}+h_i)} y_{i-1} + \frac{(x-x_{i+1}+h_{i-1}+h_i)(x-x_i)}{-h_{i-1}h_i} y_{i-1} + \frac{(x-x_{i+1}+h_i+h_{i-1})(x-x_i+h_i)}{h_i(h_{i-1}+h_i)} y_i \quad (4)$$

After simplification, the preceding equation can be written as

$$L(x) = A(x-x_i)^2 + B(x-x_i) + y_i$$

$$\text{Where } A = \frac{1}{(h_{i-1}+h_i)} \left( \frac{\Delta_i}{h_i} - \frac{\Delta_{i-1}}{h_{i-1}} \right) \quad (5)$$

and  $B = \frac{\Delta_i}{h_i} + Ah_i$

With these values of A and B, the quadratic equation (1) gives the next approximation  $x_{i+1}$

$$x_{i+1} = x_i + \frac{-B \pm \sqrt{B^2 - 4Ay_i}}{2A} \quad (6)$$

Since Eqn (6) leads to inaccurate results, we take the equivalent form

$$x_{i+1} = x_i - \frac{2y_i}{B \pm \sqrt{B^2 - 4Ay_i}} \quad (7)$$

This Equation (7) gives the next approximation to the root. In eqn (7), the sign in the denominator should be chosen so that the denominator will be largest in magnitude.